

External Prosthesis, Robotic Limb, or Orthothosis in Heel Strike to Toe-Off Walking Sequence

Figure 1

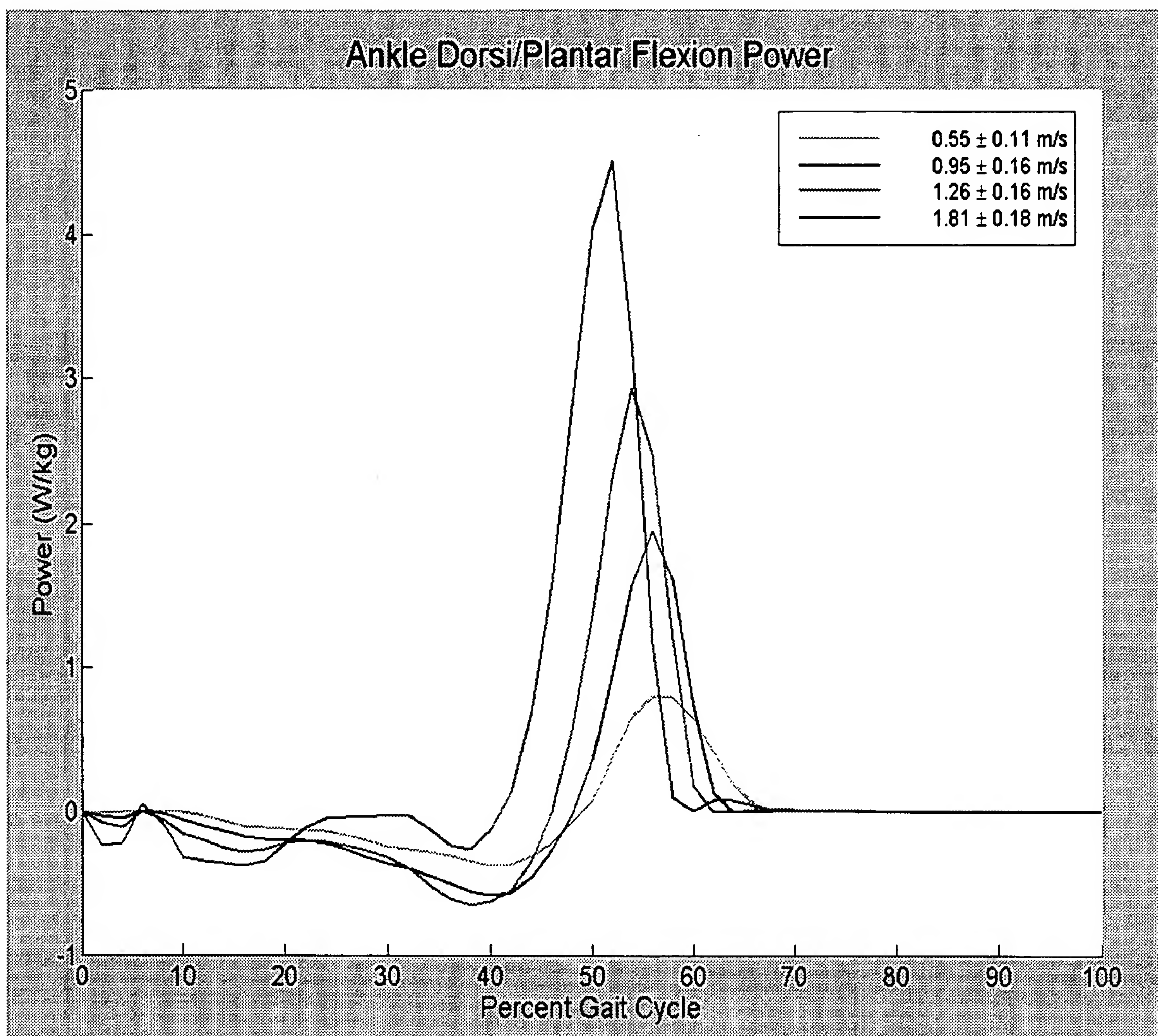
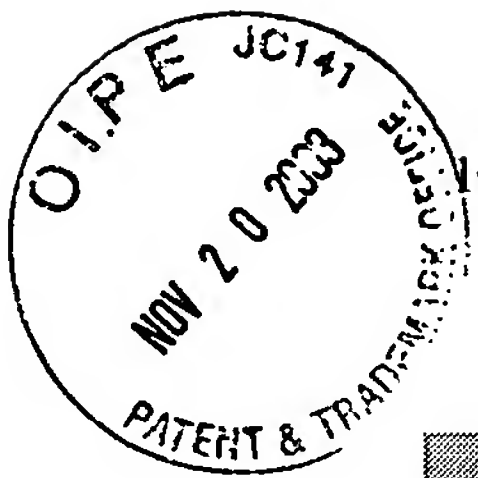


Figure 2

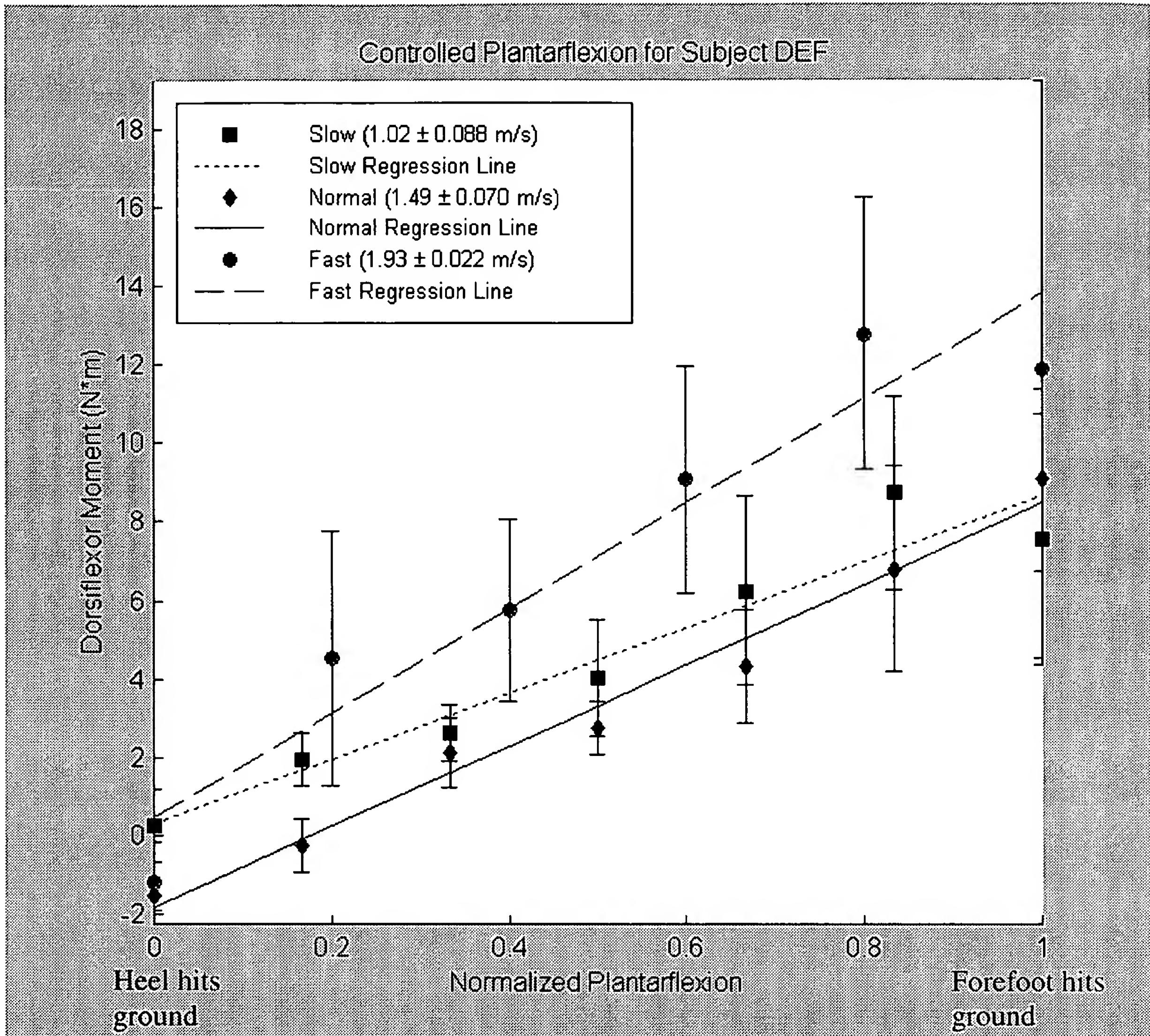
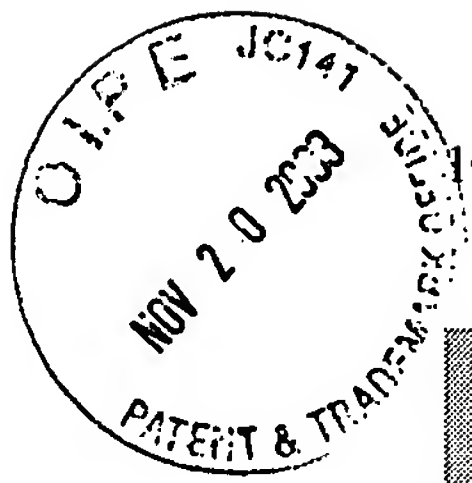
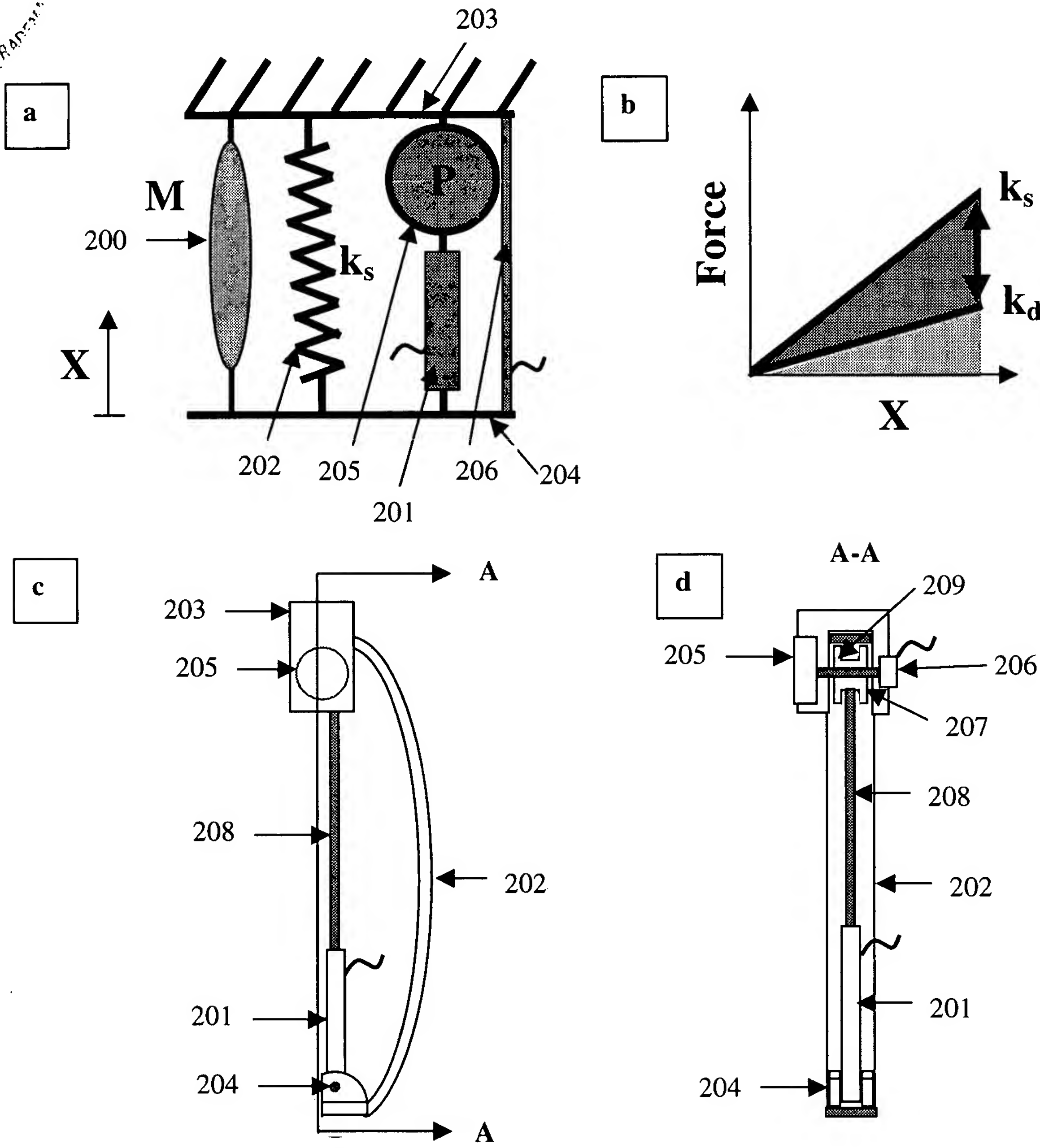


Figure 3

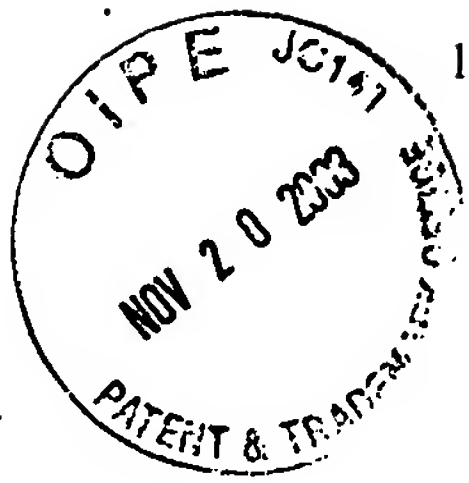
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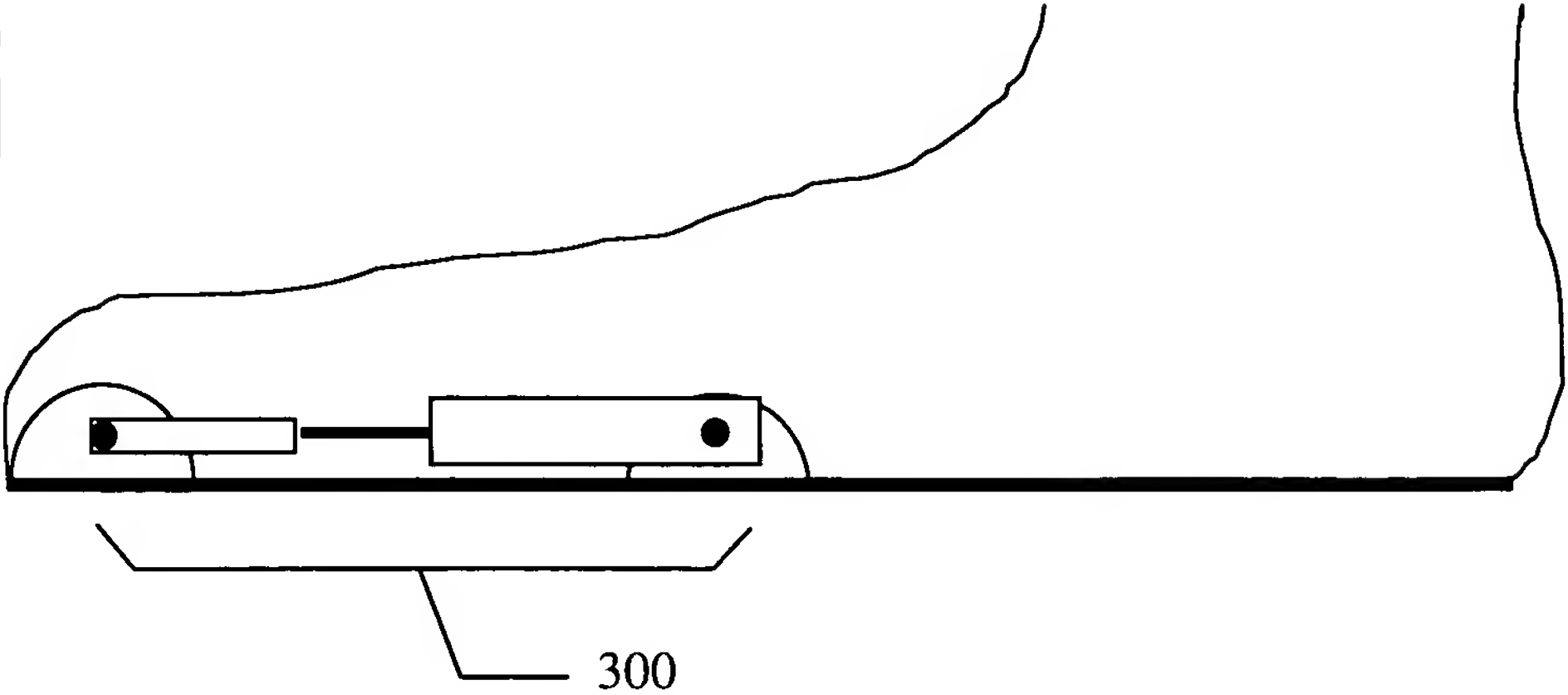
Prosthetic Mechanisms Designed to Power Plantar-flex

Figure 4

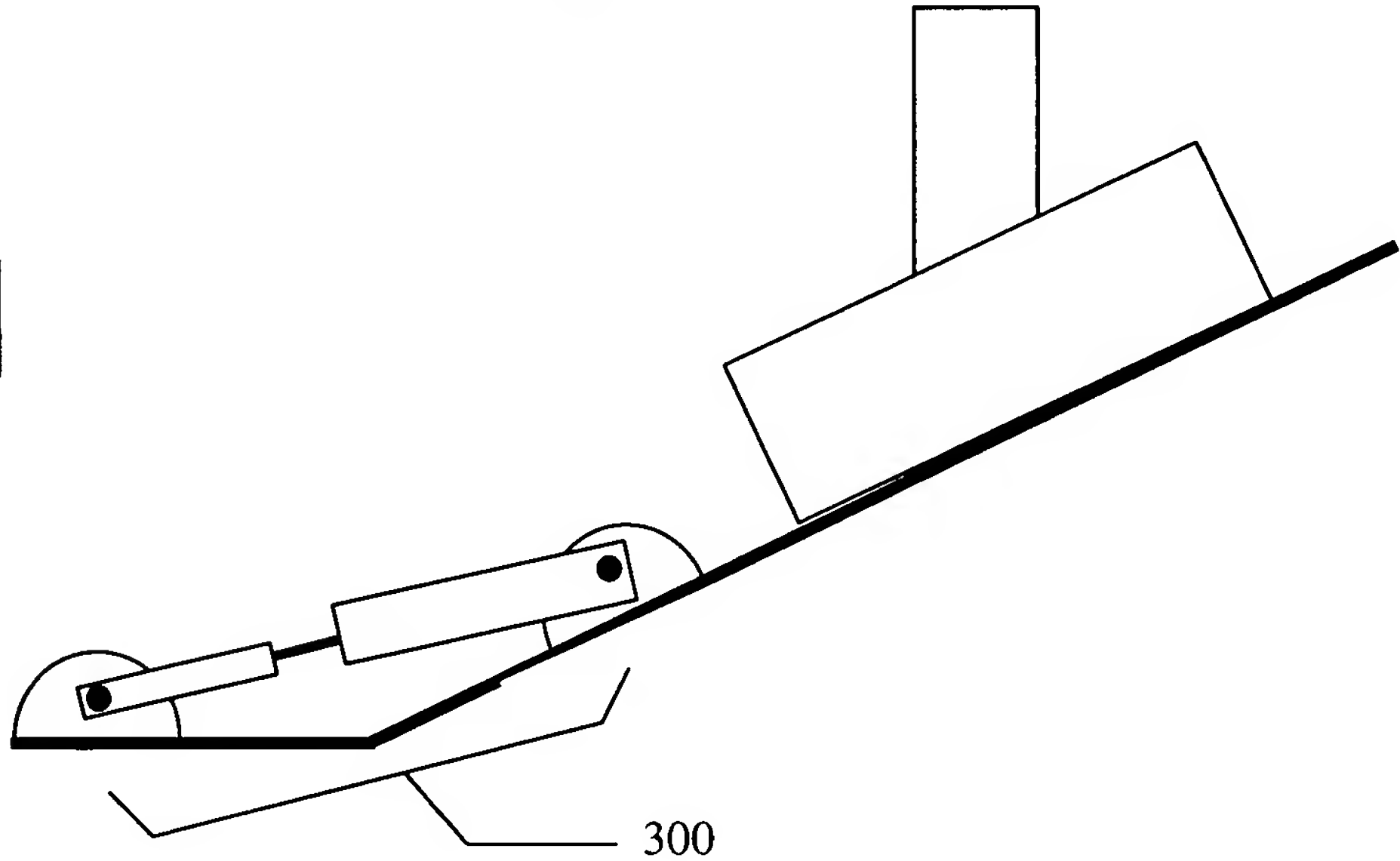




a

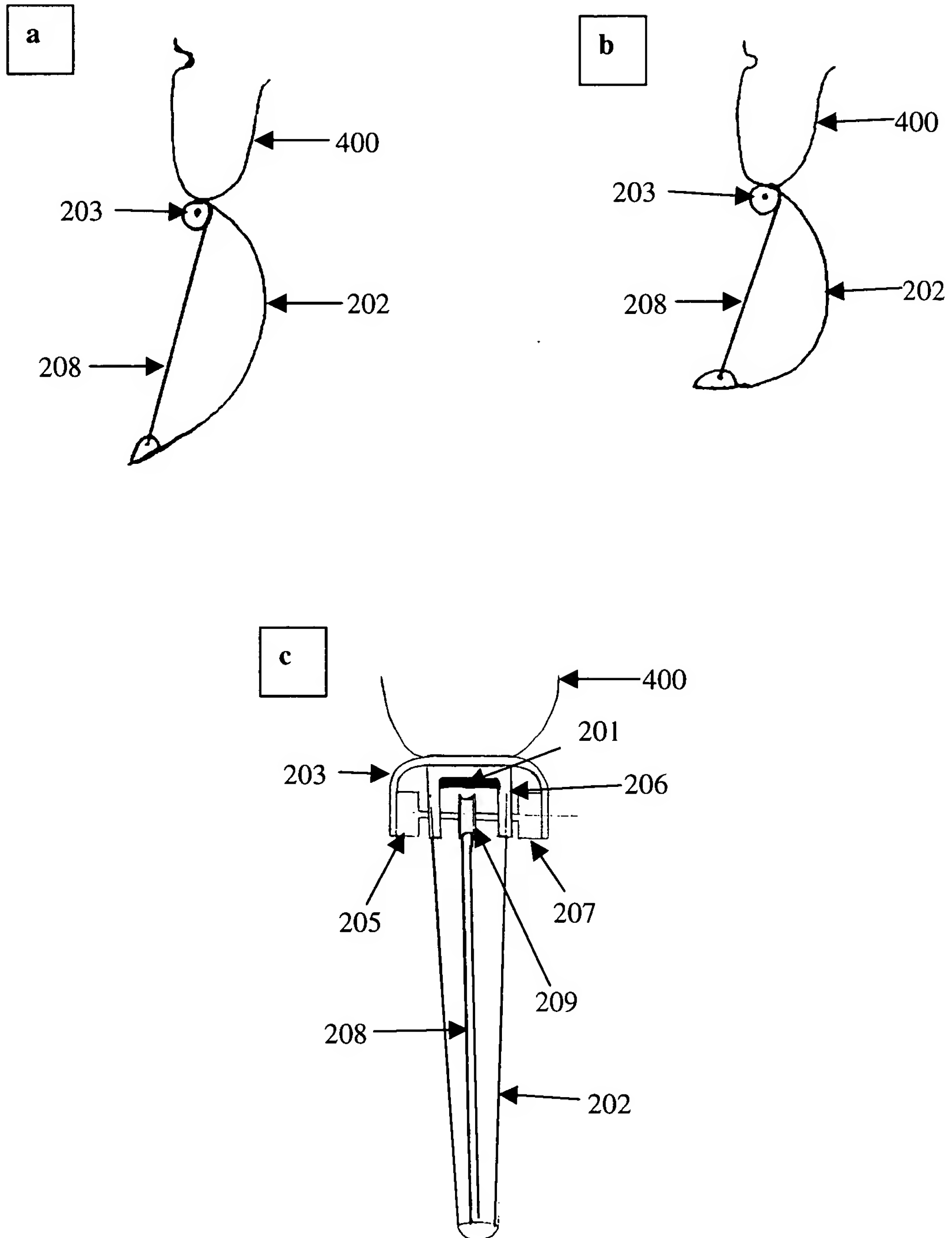
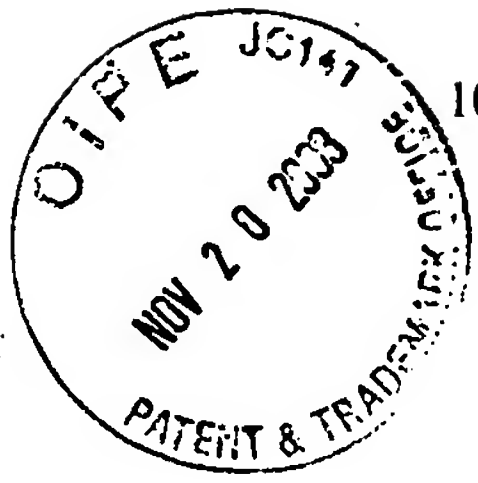


b



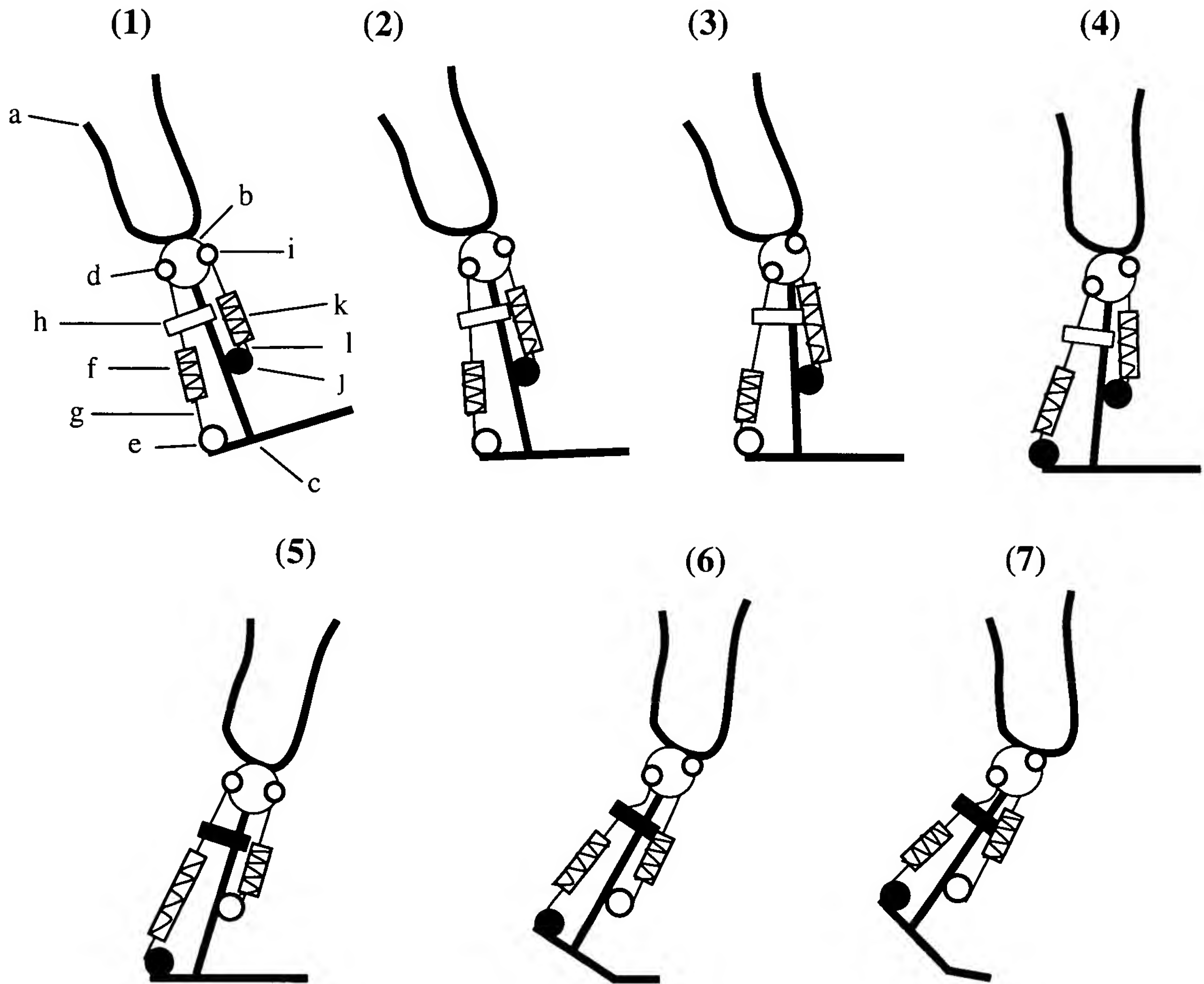
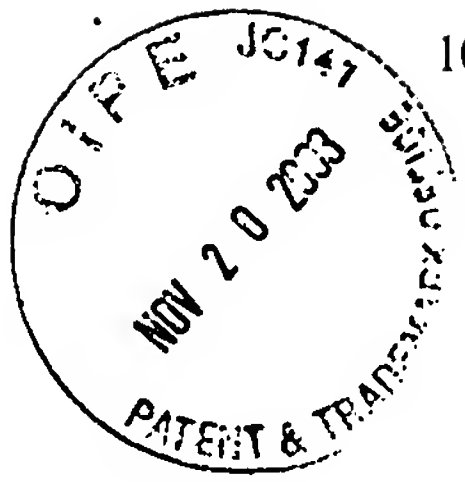
Catapult Leg Prosthesis for Walking, Running, and Jumping

Figure 5



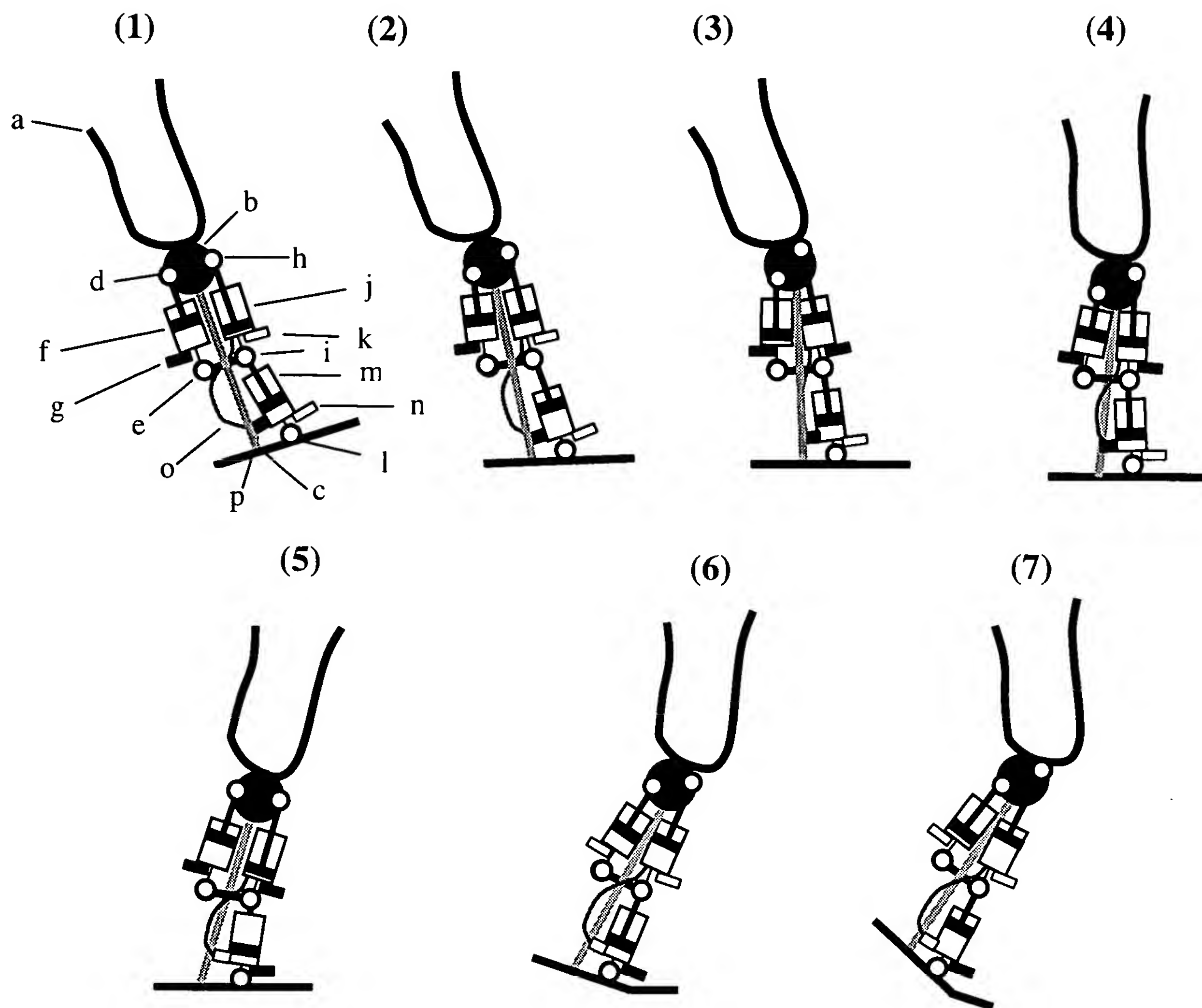
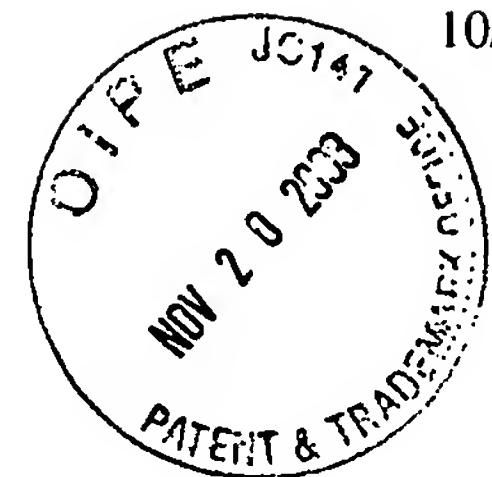
Catapult Leg Prosthesis for Walking, Running, and Jumping

Figure 6



External, Bi-articular Transfemoral Prosthesis, Robotic Limb, or Orthotic Brace in Heel-Strike to Toe-Off Walking Sequence

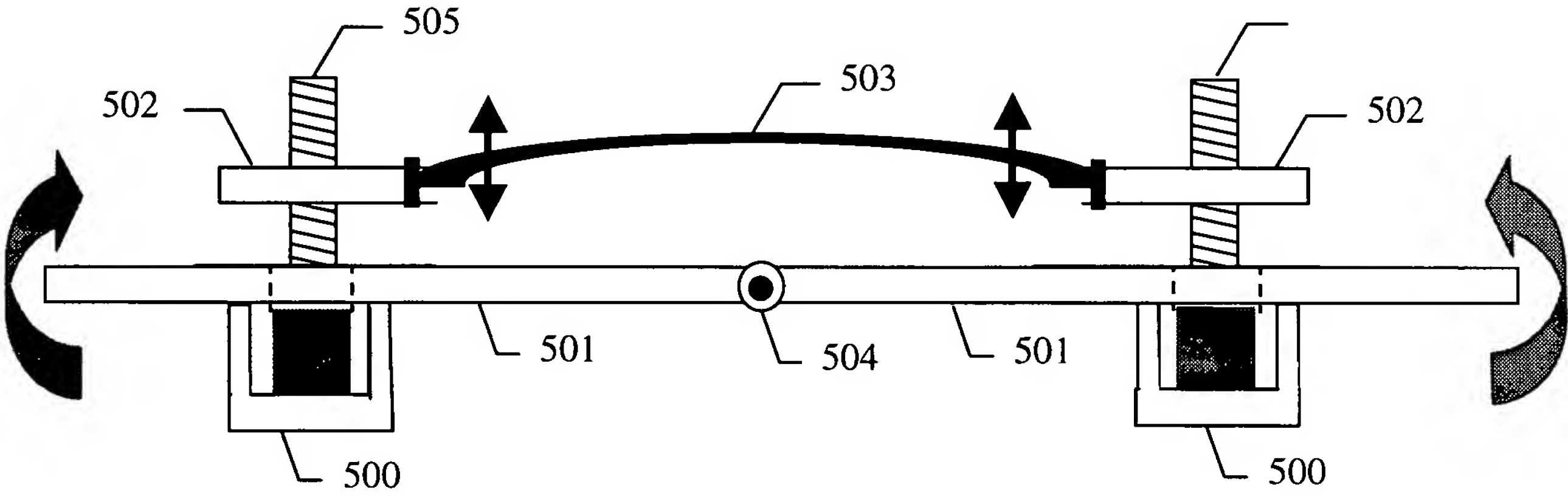
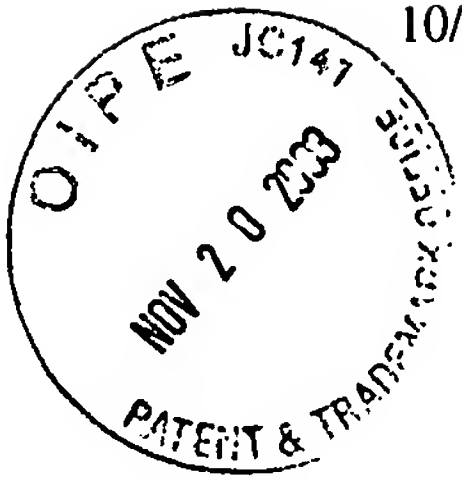
Figure 7



External, Bi-articular Transfemoral Prosthesis in Heel-Strike to Toe-Off Walking Sequence

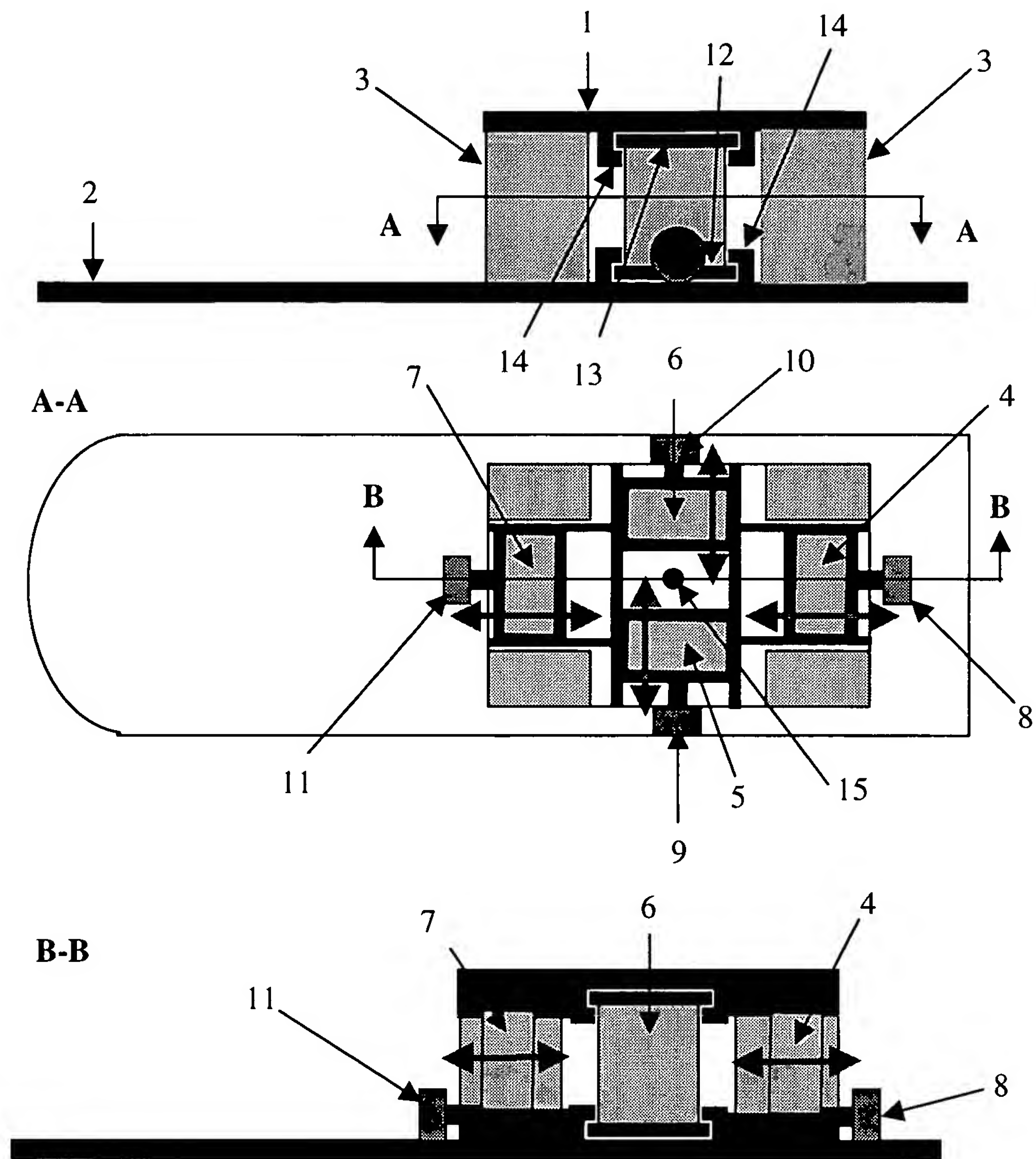
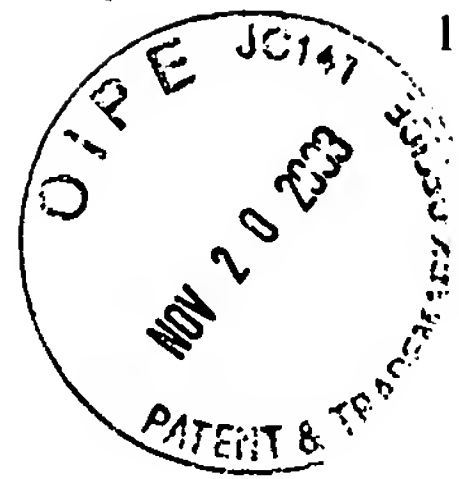
Figure 8





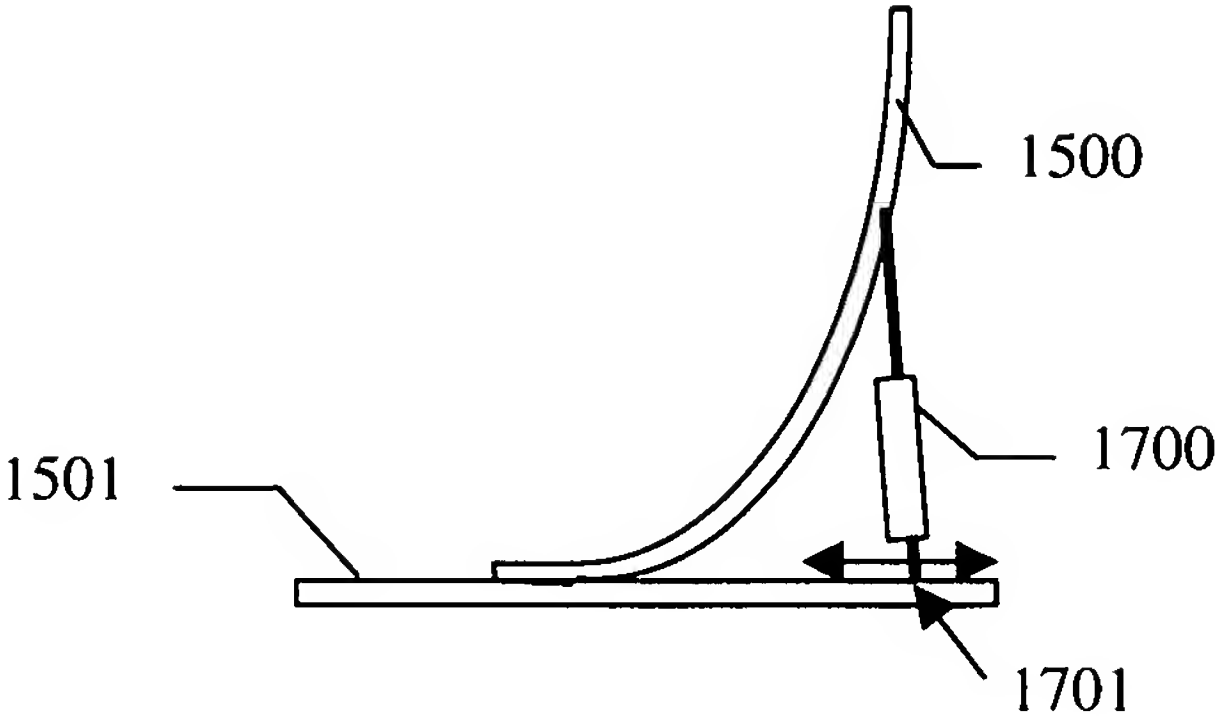
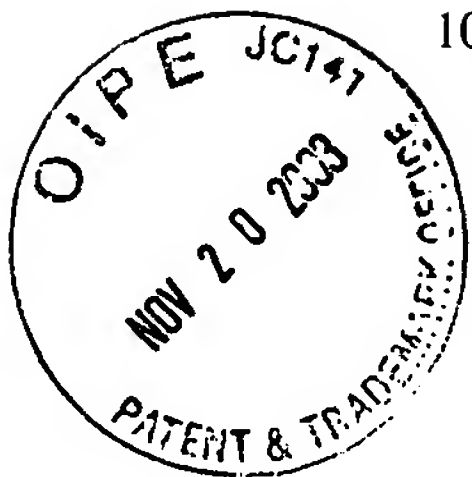
Variable Spring-Rate Joint

Figure 9



Low-Profile Prosthetic Foot

Figure 10



Example Prosthetic Ankle/Foot

Figure 11

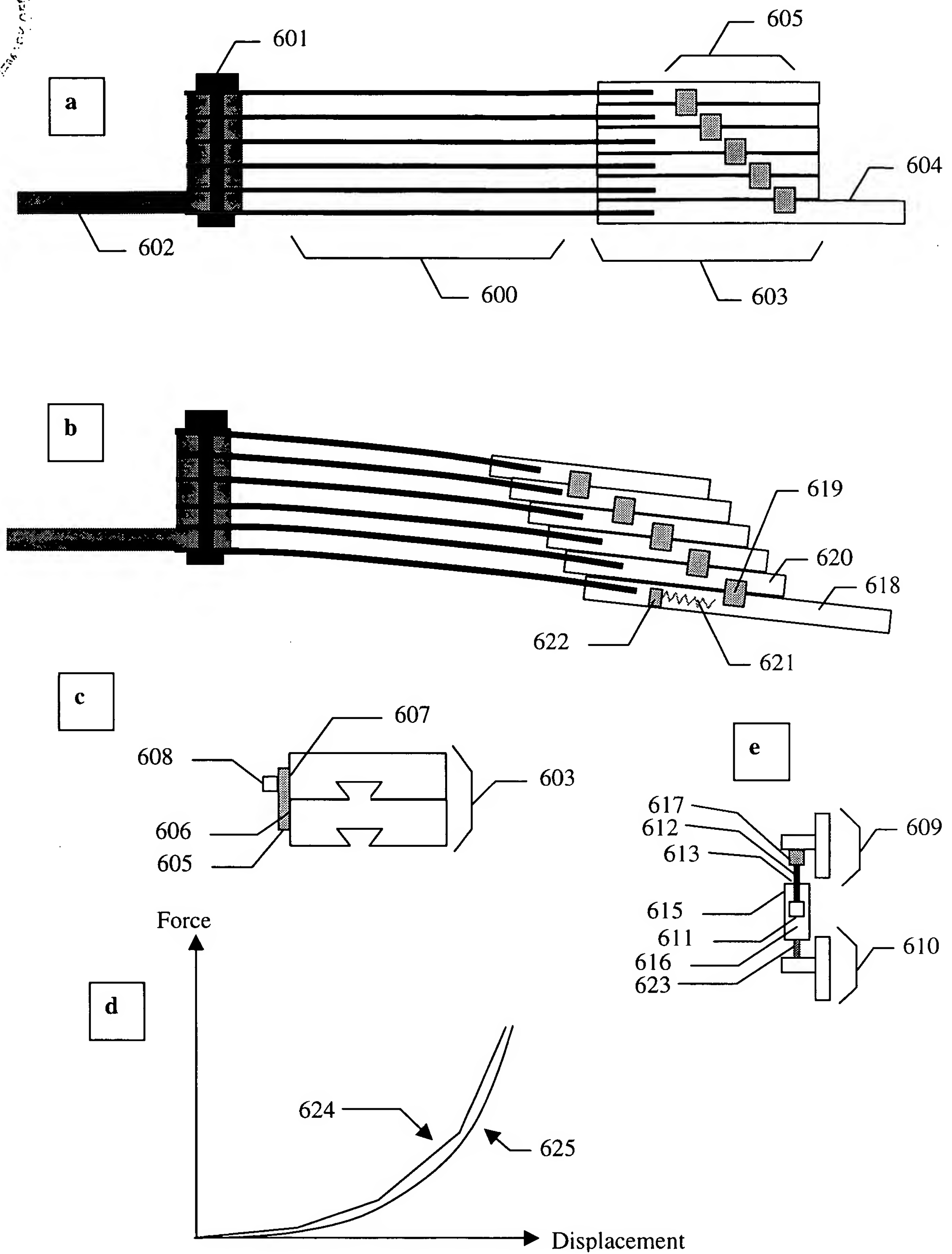
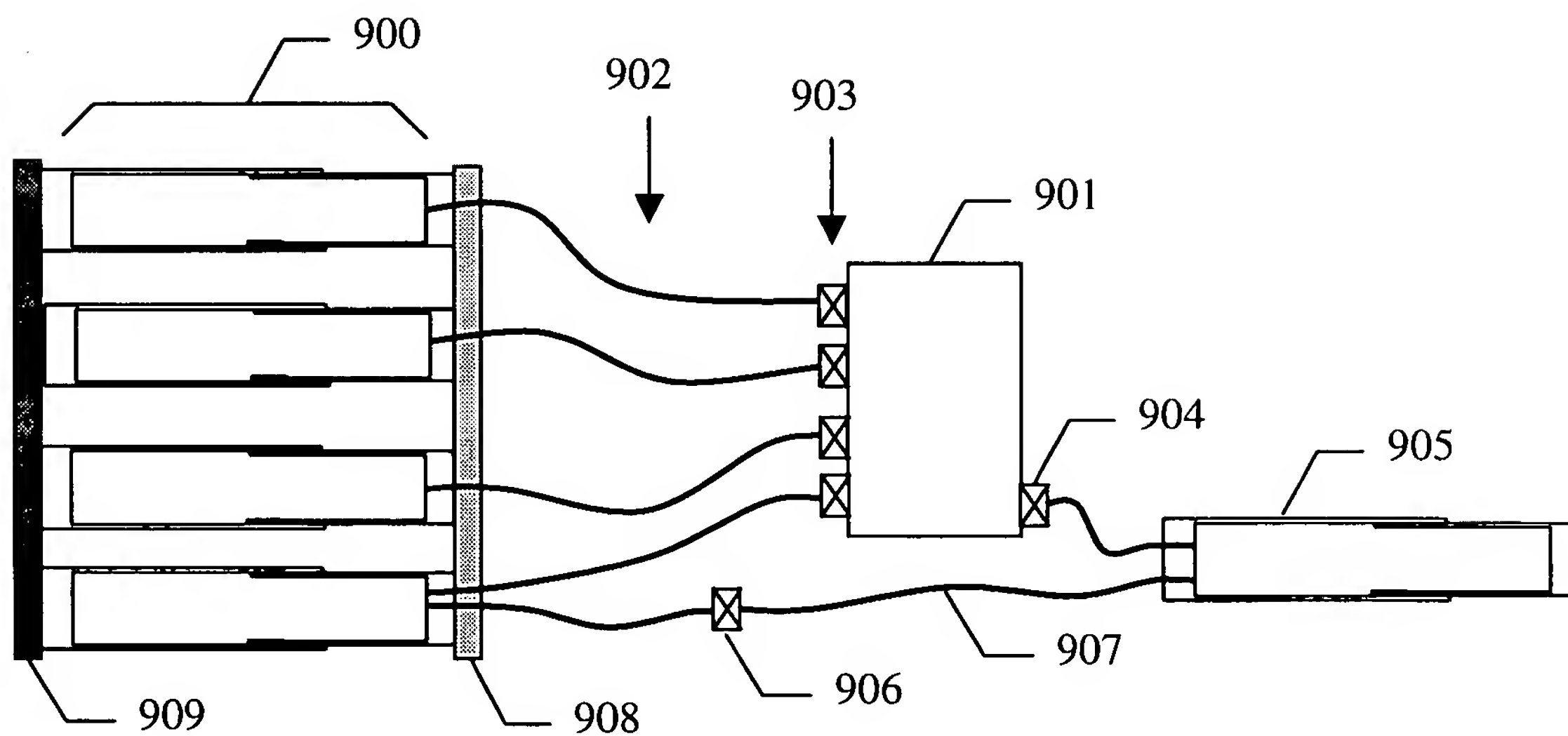
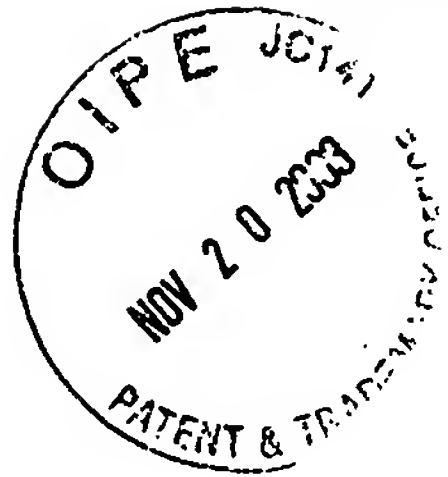
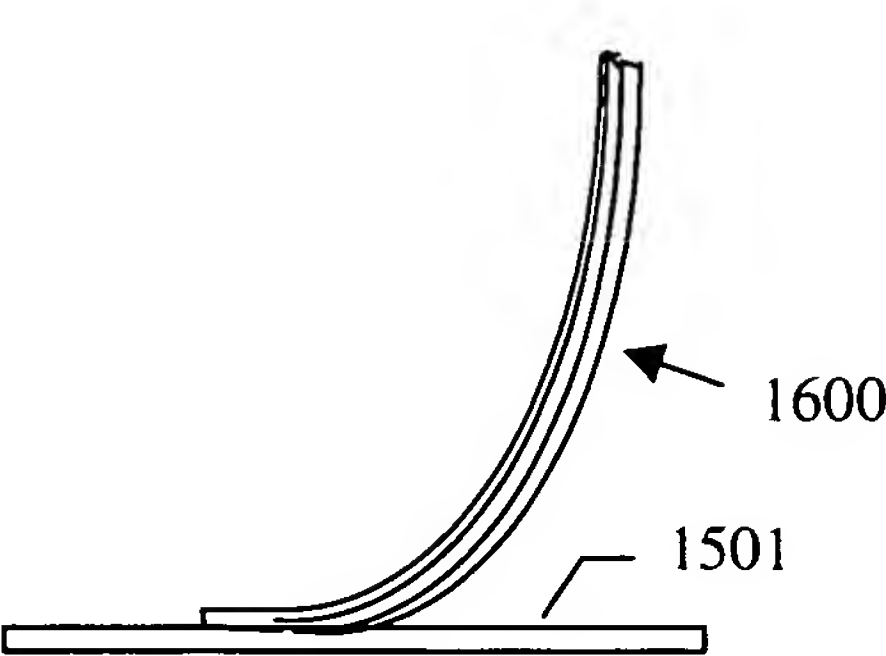
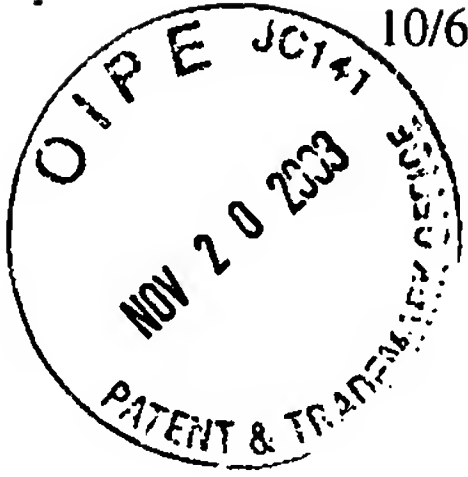


Figure 12



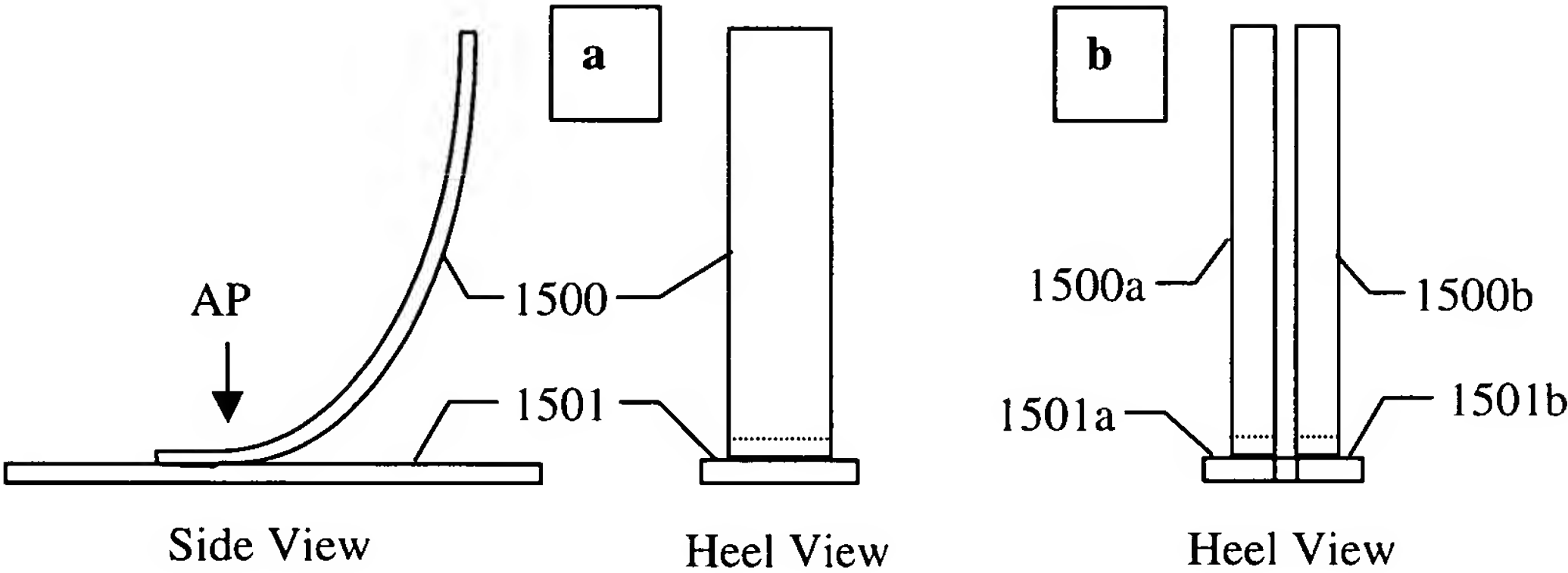
Variable-Spring-Rate Multiple-Pneumatic-Chamber and Energy Transfer System.

Figure 13



Prosthetic Ankle-Foot

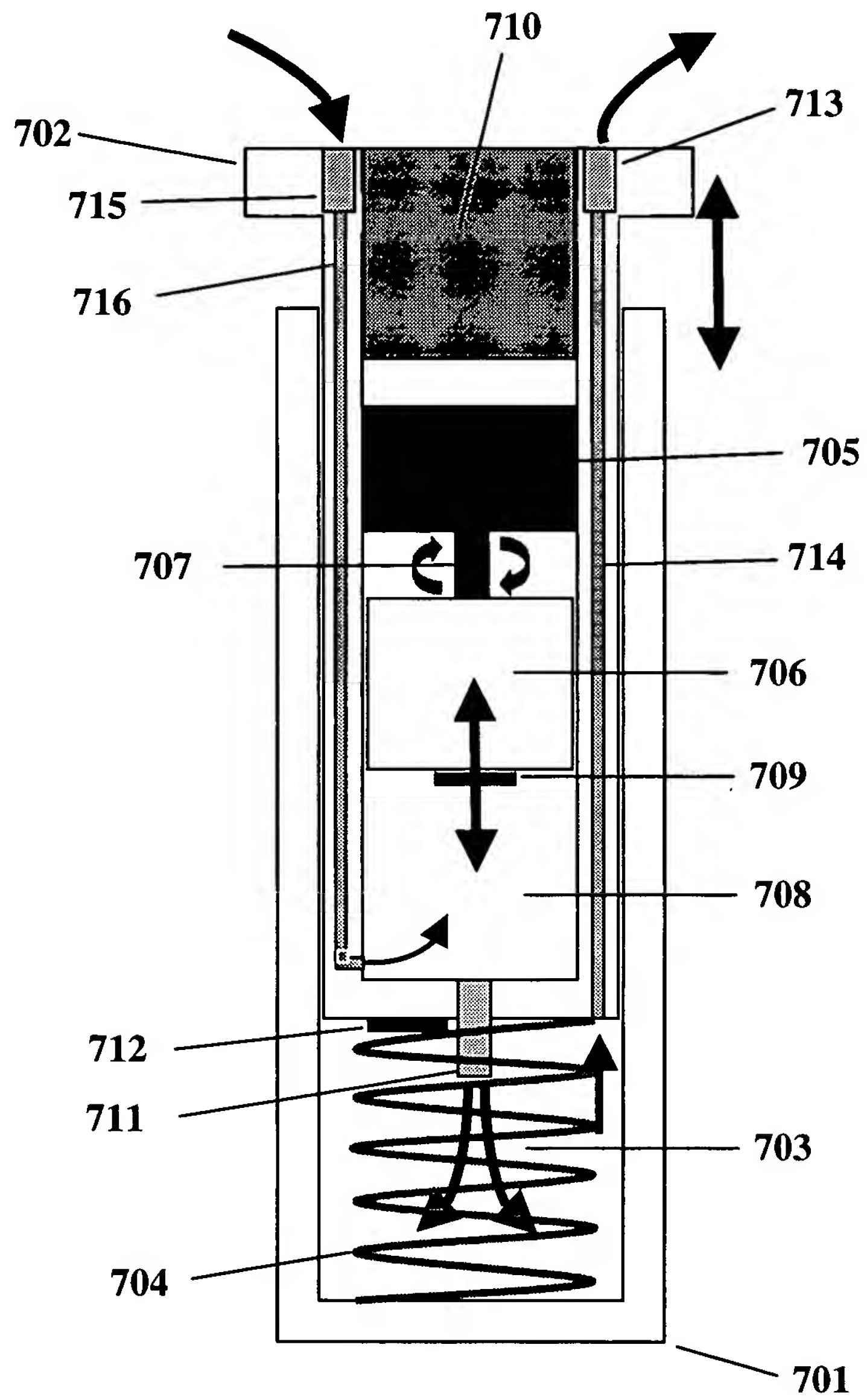
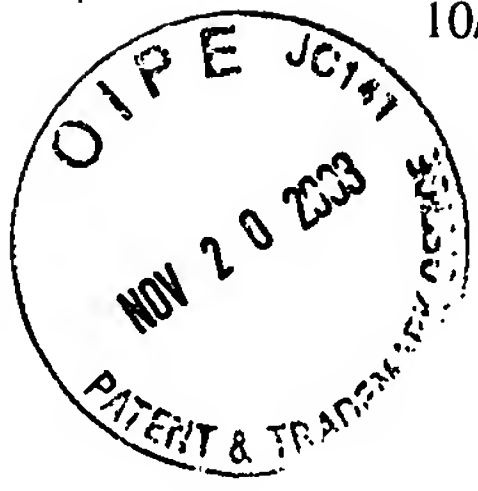
Figure 14



Prior-Art Prosthetic Ankle-Foot

Figure 15





Variable Stiffness Spring for an External Prosthesis

Figure 16